J is thus the determinant of the Jacobian of the transformation, or the "functional determinant."

The strain, N_{jk} , is defined, somewhat arbitrarily, from the difference in the squares of the lengths of line elements by:

$$2N_{jk} da_{j} da_{k} = dx_{i} dx_{i} - da_{i} da_{i}$$

$$(2.15)$$

$$N_{jk} = 1/2 \left(\frac{\partial x_{i}}{\partial a_{j}} \frac{\partial x_{i}}{\partial a_{k}} - \delta_{jk} \right)$$

Here and in the following the Einstein summation convention for repeated subscripts applies. δ_{ik} is the Kronecker delta.

Expanding the internal (strain) energy in a power series in the strains, one obtains (at constant entropy):

$$\rho_{o}[E(N,S) - E(0,S)] = 1/2 c_{ijkl}^{S} N_{ij} N_{kl} + 1/6 c_{ijklmn} N_{ij} N_{kl} N_{mn}$$

$$+ 1/24 c_{ijklmnpq}^{S} N_{ij} N_{kl} N_{mn} N_{pq} + ...$$
(2.16)

In this expression the c_{ijk}^s . . . , represent the second and higher order isentropic elastic stiffness coefficients. The first-order term is missing since the reference state is considered to be one of zero stress and strain.

We now define quantities, called thermodynamic tensions, by

$$t_{ij} = \rho_0(\frac{\partial E}{\partial N_{ij}})_s \qquad (2.17)$$

In terms of these quantities the elastic constants are

$$c_{ijkl}^{s} = (\frac{\partial t_{ij}}{\partial N_{kl}})_{s} = \frac{\partial^{2}E}{\partial N_{ij}} \frac{\partial N_{kl}}{\partial N_{kl}}$$

and similarly for the higher order coefficients. Consequently,

$$\rho_0 dE = t_{ij} dN_{ij} (dS = 0)$$

Finally, the equilibrium (non-dissipative) components of the stress are obtained from the thermodynamic tensions by the relations,

$$\sigma_{km} - (1/j) \frac{\partial x_k}{\partial a_j} \frac{\partial x_m}{\partial a_i} t_{ij} \qquad (2.18)$$

The above formulas provide isentropic constitutive relations in terms of the elastic stiffness coefficients. Other forms of constitutive relations can, of course, be derived in a similar fashion.

Low pressure acoustic measurements yield a mixed third-order constant of the form:

$$C_{ijkmpq} = \left(\frac{\partial c_{ijkm}^{S}}{\partial N_{pq}}\right)_{T}$$

where the subscript T means the derivative is taken at constant temperature. The corresponding purely isentropic constant is given by:

$$c_{ijkmpq}^{S} = C_{ijkmpq} + (T/\rho_0 C_t) c_{kmpq}^{S} \alpha_{uv} [C_{ijkmrs} \alpha_{rs} - (\frac{\partial c_{ijkm}^{S}}{\partial T})_t]$$
 (2.19)

where $C_{\mbox{t}}$ is the specific heat at constant tension and the $\alpha_{\mbox{uv}}$ are thermal expansion coefficients,

$$\alpha_{uv} = \left(\frac{\partial N_{uv}}{\partial T}\right)_{t}$$

In view of the symmetry of the stress and strain tensors, the number of subscripts can be reduced by adopting the following convention:

$$11 \rightarrow 1$$
 $32 \rightarrow 4$ $22 \rightarrow 2$ $31 \rightarrow 5$ $33 \rightarrow 3$ $21 \rightarrow 6$

This convention is employed in the following.